

**In the Specification:**

Please replace the original specification in its entirety with the substitute specification submitted herewith.

**In the Claims:**

Cancel Claims 4, 20 and 21, without prejudice.

Please rewrite the following claims in amended form:

Sub B, 1  
A  
1. (Amended) A system for controlling a load-lifting apparatus (1), having a controllable drive (2), having a load-bearing element (5) which is connected to the drive (2) and is aligned in a vertical path (Z-Z) as a result of gravitational force at least in a rest position, having a load-receiving device (7) which is connected to the load-bearing element (5), and having a regulating circuit for load-balancing purposes, characterized in that the regulating circuit for load-balancing purposes comprises a device (11) for generating a path-dependent signal (S), which contains information corresponding to a substantially vertical (Z-Z) movement of the load-bearing element (5) and serves as an input signal for controlling the drive (2) to balance a load in the vertical path.

2. (Amended) The system as claimed in claim 1, characterized in that the drive (2) is an electric motor and has the device (11) for generating the path-dependent signal (S).

3. (Amended) The system as claimed in claim 1, characterized in that the drive (2) is a fluidically acting drive device.

Sub B, 1  
A  
5. (Amended) The system is claimed in Claim 1, characterized in that the load-bearing element (5) comprises a load-bearing parallelogram in which four sub-arms are connected to one another at joints with a horizontal pivot axis and in which the angle position